

# QUALITY CONTROL SYSTEMS









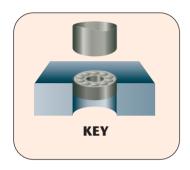


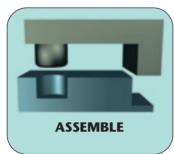
# CONTROLLING THE PARAMETERS

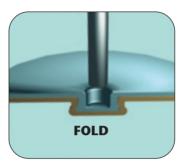
of a manufacturing process is essential for guaranteeing 100% quality

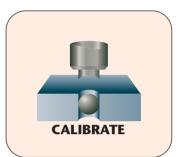
# ALFAMATIC OFFERS

a range of force/motion monitoring instruments and systems used to control the various production operations











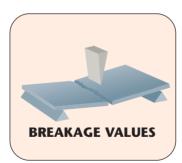














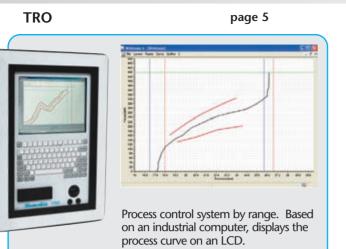
# INSTRUMENTS DESIGNED FOR A VARIETY OF PRODUCTION EQUIPMENT:

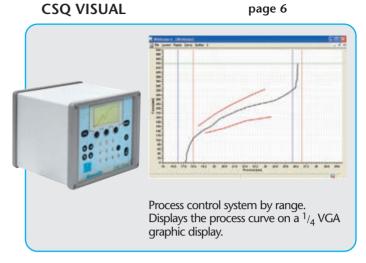
Pneumatic – hydraulic – hydropneumatic – manual presses

Screwing devices – Torque/rotation control

Test laboratories – Quality control – Prototyping – Assembly lines

# **PRODUCT RANGE**

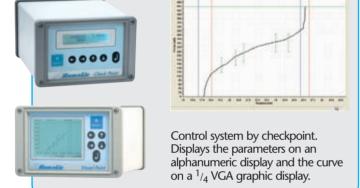






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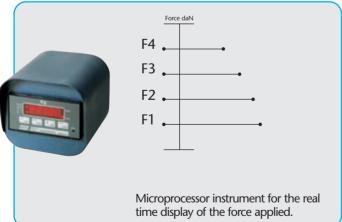
**TRO Automation** 

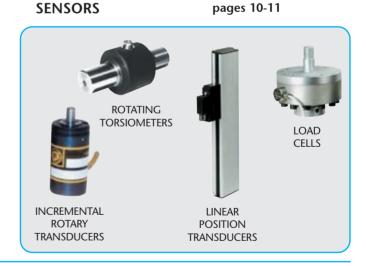


Multi-axial control module by range. For installation inside electrical cabinets.

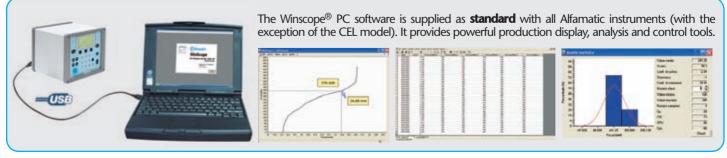
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WINSCOPE® page 9



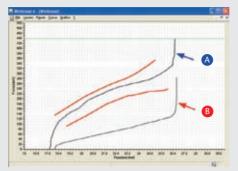
# MANAGEMENT AND CONTROL OF MANUFACTURING PROCESSES

# Management of the stop point of the press



Controls the stop and return points of the press when a specific force and/or stroke value is reached.

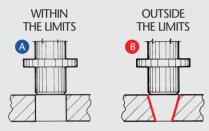
# **Assembly interference control**



The interference between two parts to be assembled is controlled throughout the entire operation.

- $\mathbf{A}$  = execution with correct interference
- **B** = execution with interference outside the limits (too loose) with the curve below the limit range

# **Geometric control** of the part



Geometric errors, if any, are displayed by non-conforming process curves.

# Control of the presence and correct position of the part



Examples of positions and associated process curves.

- A = part correctly positioned
- B = part incorrectly positioned
- = part not inserted in its seat

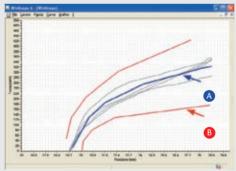


#### Non-destructive monitoring

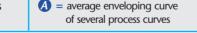


For large and expensive parts. The cycle stops whenever the monitoring curve is outside the range.

### Automatic determination of the control parameters

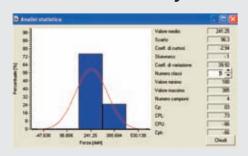


Available with manual or statistical method, with enveloping of the minimum and maximum values and definition of the average



 $\mathbf{B}$  = control range generated by assigning a specific limit to the average curve in point A

### Statistical analysis



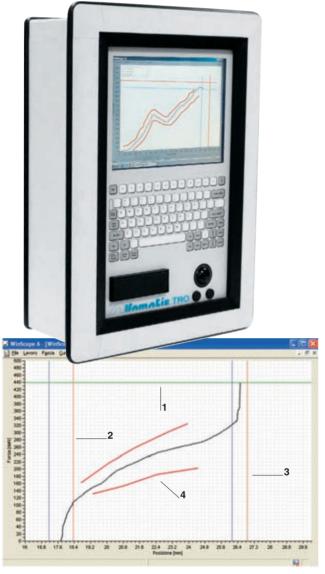
The software includes powerful functionality for the statistical analysis of the production performed (with calculations of CP/CPK, averages, variances, etc.).

# Sequential control of different processes



For parts that require several different processes to be performed in succession: the control instrument (TRO, CSQ-VISUAL, TRO Automation) automatically sets the control parameters for the specific process step.

# TRO SYSTEM



Graphic display with the WINSCOPE® program, already installed in the instrument (specifications on page 9).

#### **Performances**

Sampling frequency: > 1000 HzMaximum position detection error:  $\pm 0,01 \text{ mm}$ .

Maximum force detection error: 0,5%Number of processes that can be saved: > 1.000.000Cycle time: < 1 sec.

# **Specifications**

**Position transducer:** Incremental encoder with zero setting or 0-10V analog transducer

**Force transducer:** Load cell with 2mV/V resistor

**Power supply:** Single-phase 230 Vac

(115 Vac optional)

**Inputs:** Clean contact or opto-insulated,

24 Vdc positive voltage transistors

(PNP)

**Outputs:** Opto-insulated, 24 Vdc positive

voltage transistors (PNP)

**Dimensions:** Width: 420 millimeters

Height: 600 millimeters Depth: 210 millimeters TRO is a measurement system that provides 100% quality control of manufacturing processes. Interfaced to a position transducer and a force transducer, it continuously monitors the position/force curve and verifies that it is within a specifically positioned continuous control range.

The system consists of the following two components:

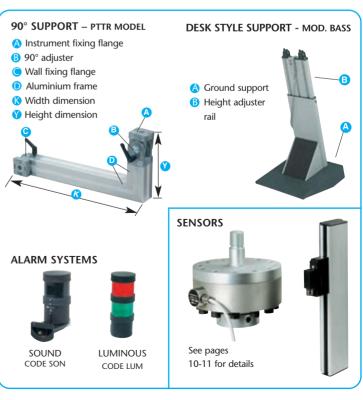
- 1) An industrial computer to enter the parameters, display and save the process curves.
- 2) A data acquisition module installed on the machine (inside the electrical cabinet) and connected to the industrial computer.

#### **Control functions**

The TRO system consists of the following functions, among others, to control the pressing process:

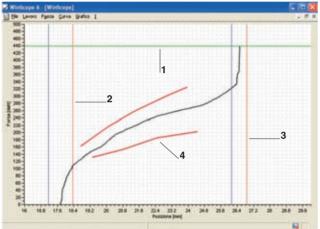
- 1 **Stop values** to control the return of the press to the TDC
- 2 **Process start control** to verify the presence and correct position of the part
- 3 **Process end limits** to control the final values of force and distance
- 4 **Control range** to verify all the process curves in real time

#### **Accessories**



# **CSQ-VISUAL SYSTEM**





Graphic display with the WINSCOPE® program, installed on a PC connected to CSQ Visual (specifications on page 9).

#### **Performances**

Sampling frequency: > 1000 Hz Maximum position detection error:  $\pm 0,01 \text{ mm}$ . Maximum force detection error: 0,5% Number of processes that can be saved: 250 (16 selected from inputs)

< 1 sec.

**Specifications** 

Cycle time:

**Position transducer:** Incremental encoder with zero

setting or 0-10V analog transducer

**Force transducer:** Load cell with 2mV/V resistor

**Power supply:** Single-phase 230 Vac

(115 Vac optional)

**Inputs:** Clean contact or opto-insulated,

24 Vdc positive voltage transistors

(PNP)

**Outputs:** Relay with 24 Vdc common or

positive voltage transistor (inquire

about availability)

Communication ports: RS232 serial or USB

**Dimensions:** Width: 175 millimeters

Height: 205 millimeters Depth: 240 millimeters CSQ-VISUAL is a measurement system that provides 100% quality control of manufacturing processes. Interfaced to a position transducer and a force transducer, it continuously monitors the position/force curve and verifies that it is within a specifically positioned continuous control range.

The system architecture is based on a data monitoring and analysis multiprocessor and is connected directly to the sensors.

The instrument itself supplies the power for the machine valves, the transducers and limit stop and warning lights, if any.

#### **Control functions**

The CSQ-VISUAL system consists of the following functions, among others, to control the pressing process:

- 1 **Stop values** to control the return of the press to the TDC
- 2 **Process start control** to verify the presence and correct position of the part
- 3 Process end limits to control the final values of force and distance
- 4 **Control range** to verify all the process curves in real time

#### 6-cells version

**CSQ-VISUAL** is also available in a 6-cells configuration for the simultaneous control and display of up to six load cells (using a single position transducer).

#### **Accessories**



# **CHECK POINT SYSTEM**



Graphic display with the WINSCOPE® program, installed on a PC connected to CHECK POINT (specifications on page 9).

#### **Performances**

Sampling frequency: > 1000 HzMaximum position detection error:  $\pm 0,01 \text{ mm}$ . Maximum force detection error: 0,5%

Number of processes

that can be saved: 16 (selected from the inputs)

Cycle time: < 1 sec.

# **Specifications**

**Position transducer:** Incremental encoder with zero

setting or 0-10V analog transducer

Force transducer: Load cell with 2mV/V resistor

**Power supply:** Single-phase 230 Vac

(115 Vac optional)

**Inputs:** Clean contact or opto-insulated,

24 Vdc positive voltage transistors

(PNP

**Outputs:** Relay with positive voltage 24 Vdc

common

Communication ports: RS232 serial

**Dimensions:** Width: 175 millimeters

Height: 115 millimeters Depth: 200 millimeters CHECK POINT (version also available with a VISUAL POINT graphic display) is a measurement system that provides 100% quality control of manufacturing processes. Interfaced to a position transducer and a force transducer, it verifies that the pressure applied is within the specific limits **in eight predetermined positions**.

CHECK POINT can also be connected to a personal computer via the WINSCOPE® software to display the curves and modify the parameters.

The instrument itself supplies the power for the machine valves, the transducers and limit stop and warning lights, if any.

#### **Control functions**

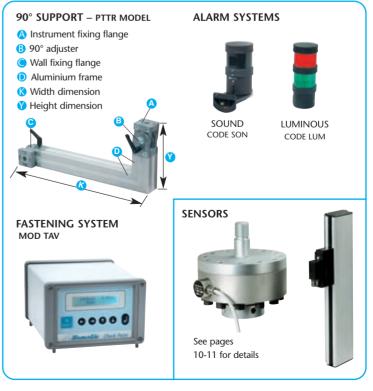
The CHECK POINT system consists of the following functions, among others, to control the pressing process:

- 1 **Stop values** to control the return of the press to the TDC
- 2 **Process start control** to verify the presence and correct position of the part
- 3 Process end limits to control the final values of force and distance
- 4 Check Points to verify all the process curves in real time

# VISUAL POINT with graphic display

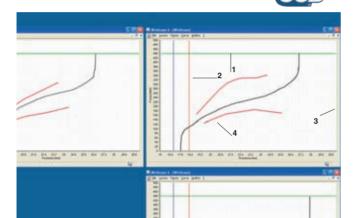


## **Accessories**



# TRO AUTOMATION SYSTEM





 $\label{eq:Multi-curve} \mbox{Multi-curve display with the WINSCOPE} \mbox{\ensuremath{^{\circledcirc}}} \mbox{\ensuremath{program}}, \mbox{\ensuremath{installed}} \mbox{\ensuremath{normal}} \mbox{\ensuremath{a}} \mbox{\ensuremath{e}} \mbox{\ensuremath$ 

TRO Automation is a control instrument used for **assembly lines and stations**. Able to control several pressure axes simultaneously, the TRO Automation system is a module that is installed to DIN standards rails inside an electrical cabinet.

Interfaced to a position transducer and a force transducer, the system verifies that the working stroke is within a specific range. It also stops the machine if a specific force and/or distance is reached.

#### **Control functions**

The TRO AUTOMATION system consists of the following functions, among others, to control the pressing process:

- 1 **Stop values** to control the return of the press to the TDC
- 2 **Process start control** to verify the presence and correct position of the part
- 3 Process end limits to control the final values of force and distance
- 4 **Control range** to verify all the process curves in real time

#### **Performances**

Sampling frequency: 2 x 1000/sec.

Maximum position detection error: 0,01 mm.

Maximum force detection error: 0,5%

Number of processes

that can be saved: 32 (selected from the inputs)
Cycle time: < 1 sec.

# **Specifications**

Position transducer: Two inputs per incremental

encoder with zero setting and two inputs per 0-10V analog

transducer

Force transducer: Two inputs per load cell with

2mV/V resistor

**Power supply:** 24 Vdc

**Inputs:** Clean contact or opto-insulated,

24 Vdc positive voltage

transistors (PNP)

**Outputs:** Opto-insulated, 24 Vdc positive

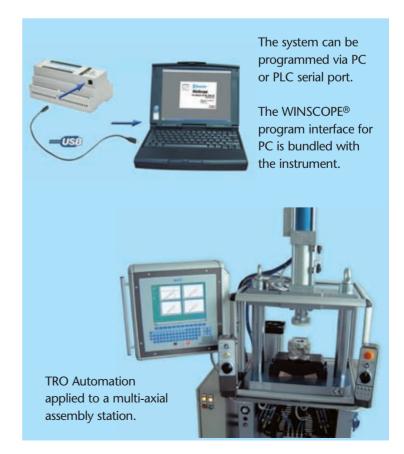
voltage transistor

Communication ports: USB, Ethernet, RS485, RS232

(inquire about availability)

**Dimensions:** Width: 158 millimeters

Height: 71 millimeters Depth: 90 millimeters



# **CEL SYSTEM**



Displays the peak pressure value

Displays the force applied

Stops the unit when the force value entered is reached

The CEL system is composed of a load cell and a microprocessor for the real time display of the force applied. The force value can be preselected in accordance with the power unit used.

In the standard configuration, the instrument has four programmable set points with a relay output to connect to a PLC.

#### **Specification (instrument)**

Accuracy	± 0,5%
Linearity error	± 0,5%
Programmable set points	4
Programmable hystereses	4
Conversions per second	50
Relay outputs	4
Power supply	230Vac
Maximum absorption	10VA
Protection class	IP40
D: :	WIDTH

Dimensions WIDTH: 180 mm. HEIGHT: 150 mm.

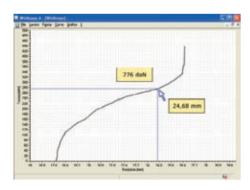
DEPTH: 200 mm.

# **WINSCOPE®**

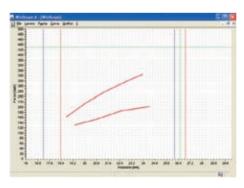
**WINSCOPE®** is the PC interface program that is supplied as standard with all the control instruments (with the exception of the CEL system).

Designed to increase the capacity of the instruments, the software allows for the easy programming of the control parameters and provides an excellent display of the process curves (on the PC).

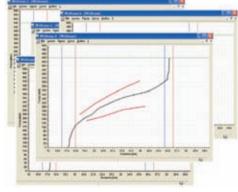
Below are a few advantages resulting from the use of WINSCOPE® with the control instruments:



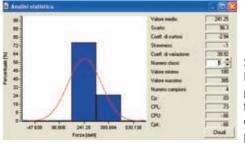
Analyzing the curve
Real time display of the process curve. It
also monitors the force value at every point
of the stroke.



**Entering the parameters**The control parameters can be entered and modified via the PC mouse and keyboard.



**Archiving the curves**Winscope® can save process curves of the entire production or part of it.



**Statistical analysis**Powerful graphic/
parametric functionality
for the statistical analysis
of the production
performed.



**Database**The production data can be archived in an ACCESS database.

# THE SENSORS

# PIEZORESISTANT LOAD CELLS FOR STATIC AND DYNAMIC APPLICATIONS



Piezoresistant load cell to monitor the thrust force. Complete with fastening flange and lower tang with anti-rotation device in cadmium-plated C40 steel. Can be supplied with SIT calibration certification (upon request).

Model	TC4 5	TC4 10	TC4 25	TC4 50	TC4 100	TC4 200	TC4 300	TC4 500	TC4 750	TC4 1000
NOMINAL FORCE KN	5	10	25	50	100	200	300	500	750	1000
REPEATABILITY					±0.29	6 F.S.				
HYSTERESIS					±0,059	% F.S.				
NOMINAL SENSITIVITY					2m\	V/V				
CALIBRATION LIMIT					±0,19	6 F.S.				
INPUT RESISTANCE			800 ±20					430 ±2	0	
OUTPUT RESISTANCE		705 ±2 352 ±2								
STANDARD POWER SUPPLY		10 V								
NOMINAL POWER SUPPLY		1-15 V								
MAXIMUM POWER SUPPLY		18 V								
MECHANICAL LIMIT VALUES IN RELATION TO NOMINAL FORCE										
service force		120%								
limit force		150%								
breaking force		>300%								
dynamic limit force		75%								
MAXIMUM RISE TO NOMINAL FORCE	- 0.	.06 mm		- 0.09 n	nm	-	0.17 mr	n	- 0.23	3 mm
NOMINAL TEMPERATURE RANGE	-10/+40°C									
WEIGHT	1	,60kg		2,45k	g		5,80kg		16,	5kg
PROTECTION CLASS	IP67									
DYNAMOMETRIC MATERIAL	Stainless Steel									
CABLE LENGTH	5 m									

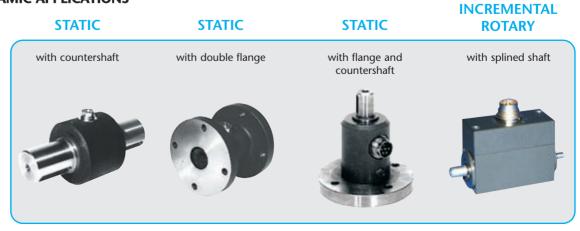
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MODEL TC4						
	5 - 10 - 25	50	100	200 - 300 - 500	750 - 1000	
Α	16	20	25	30	40	
В	M12x1,5	16x1,5	20x1,5	M27x2	M36x2	
С	18	22	28	35	45	
D	12	16	20	27	35	
Е	8	10	12	15	20	
F	M6	M8	M8	M8	M10	
G	100	127	127	165	230	
Н	16	20	26	33	43	
- 1	12	16	20	27	35	
L	16	20	25	30	40	
М	M12x1,5	M16x1,5	M20x1,5	M27x2	M36x2	
Ν	21	22	22	23	24	
V	70	75	85	110 - 155*	190	

<sup>\*</sup>Applies to model 500

# **TORSIOMETERS**FOR STATIC AND DYNAMIC APPLICATIONS

Torque sensors. STRAIN GAUGE measurement principle. Monitoring range from 1 to 2000 Nm



#### THE SENSORS **INCREMENTAL LINEAR TRANSDUCER - RACK AND PINION SYSTEM**



Linear position transducer with pre-assembled rack and pinion encoder system. Square wave incremental output. Measurement monitoring range between 0-34000 mm. Available with standard or customized supports for fastening to the movable part of the machine.

## **Specifications**

Type Incremental bidirectional with zero setting Standard stroke (mm): 200 mm (different strokes upon request)

Output: 88C30 type driver

0.01 mm with x4 external multiplication Resolution:

(different resolutions upon request)

With connector located on cursor Electrical connections:

Maximum detection speed: 20 m/min Max. permissible acceleration: 15 m/s<sup>2</sup> Start-up force: 6 N Max. error over entire stroke:  $\pm 10 \mu m$ 

Operating temperature: 0-71°C Maximum frequency: 60 kHz

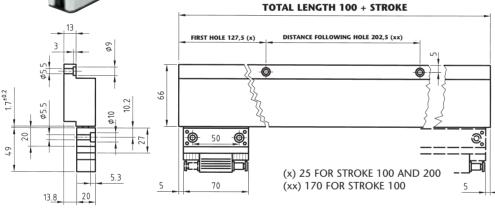
Power supply: 8-15V (different power supply voltages upon request)

Maximum mA consumption: 120 mA

Weight: 4700 grams/meter

COD CR80 ...

#### **Incremental** rotary transducers



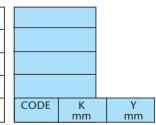
Customized fastening supports upon request

# STANDARD INCREMENTAL ENCODER MINIATURE INCREMENTAL ENCODER HIGH-RESOLUTION INCREMENTAL ENCODER ROBUST INCREMENTAL ENCODER SERIES E4 SERIES R3

#### PART NUMBERS FOR ORDERING

#### **CONTROL SYSTEMS**

CONTROL SYSTEM	TRO - CSQ VISUAL - CHECK POINT - VISUAL POINT - TRO A CEL		
	SOUND code SON		
ALARM SYSTEM	LUMINOUS code SON		
FASTENING SYSTEM	STAND code BASS - WITH FEET code TAV		
fastening system	90° SUPPORT code PTTR		



#### **SENSORS**

LOAD CILLS	Standard flanges code TC4			
LOAD CELLS	Special flanges code FLTC4			
LINEAR TRANSDUCERS	Encoder code CR - 80			
ROTARY TRANSDUCERS	series M1 - S2 - R3 - C4 - C5			
TORSIOMETERS	mod. SPA - FDS - AFS - AIR			

CODE	STROKE mm

# **PRODUCTION PROGRAM**













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